

NeuLat

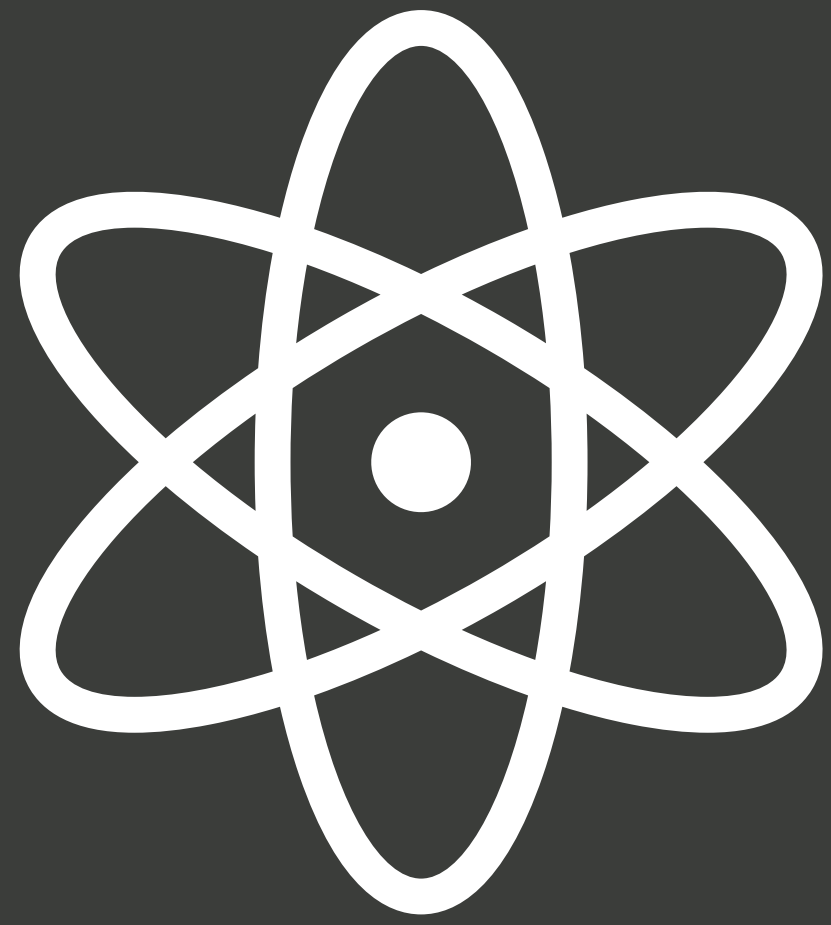
A toolbox for **Neural** samplers in **Lattice** field theories

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Talk based on: <https://pos.sissa.it/453/286/pdf>

Normalizing Flows for LFT

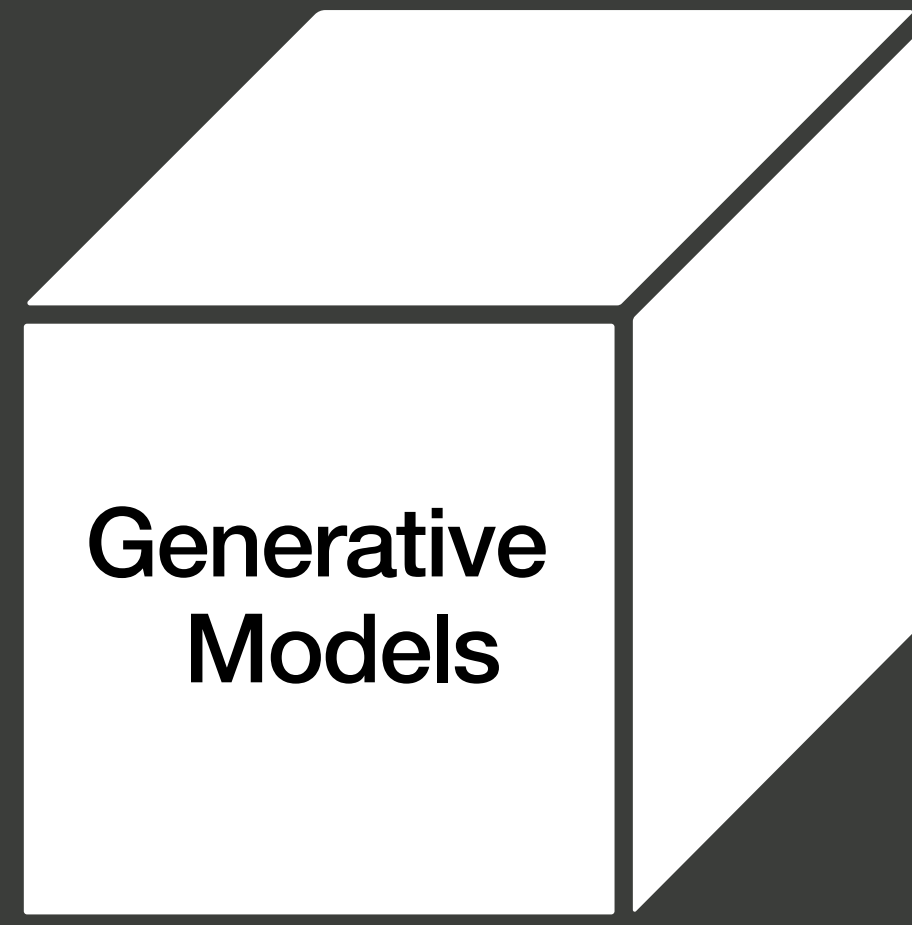
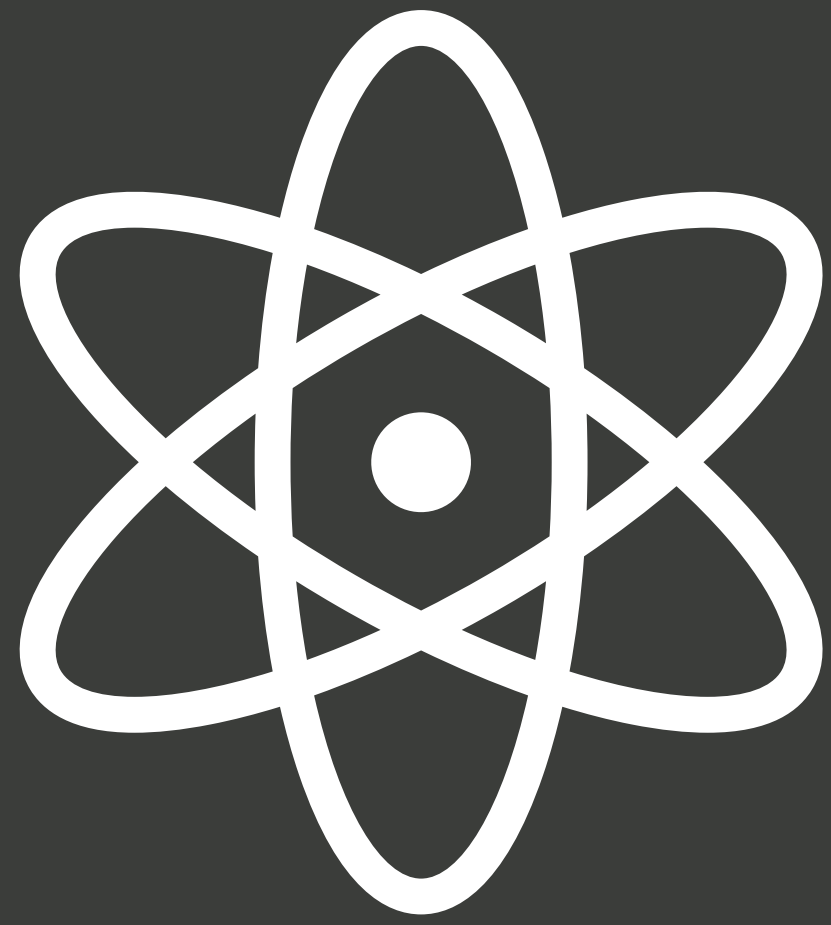


Input:

- Action* $S[U]$ ✓
- Samples (HMC) ⚠

*Here U should denote generalized field configurations e.g., scalar fields, gauge fields.

Normalizing Flows for LFT



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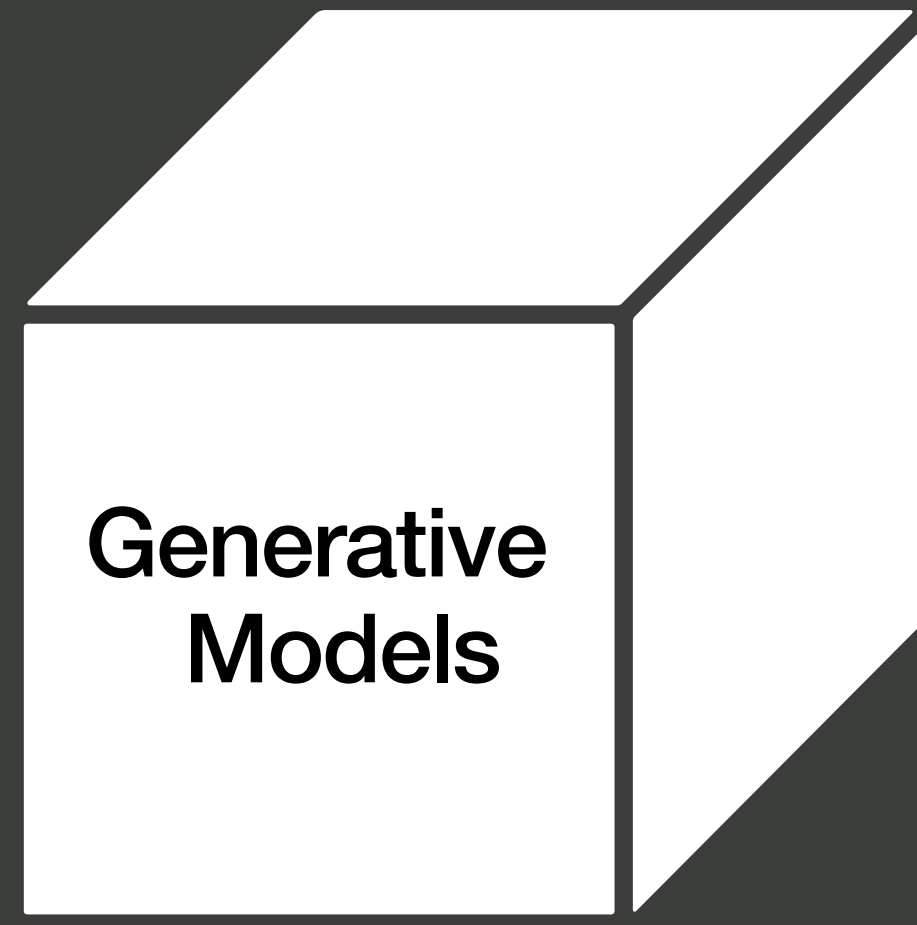
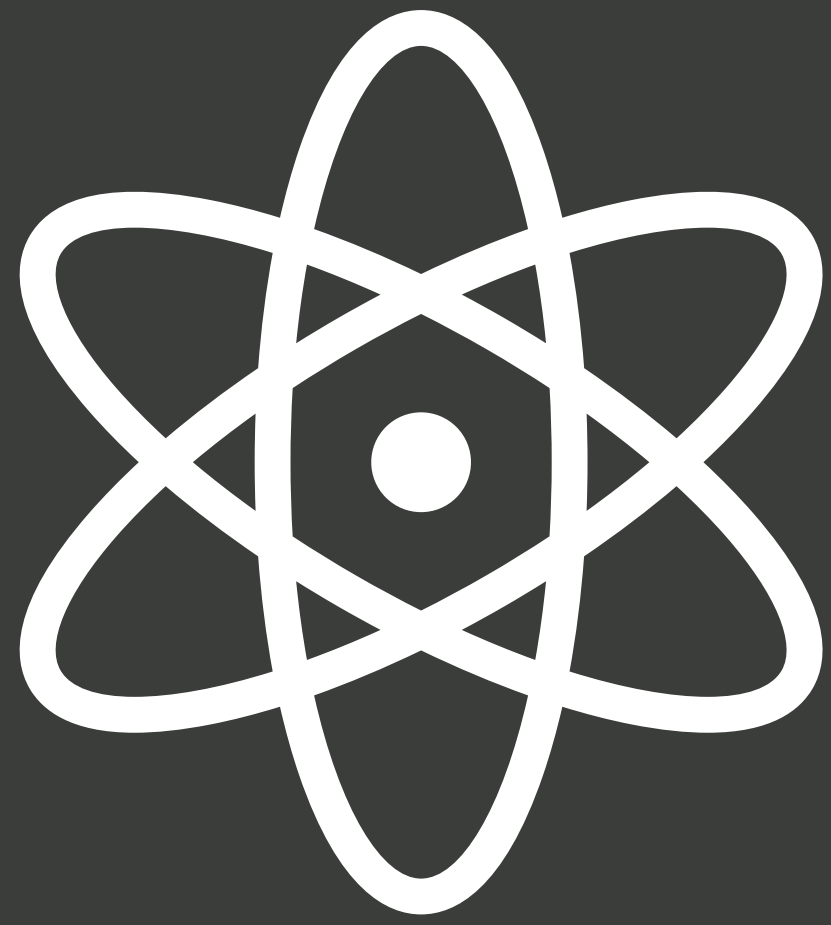
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ML black(-box) magic:

- Train generative models
 - Normalizing Flows
 - Autoregressive Models
 - Diffusion Models
- Learn normalized densities

Normalizing Flows for LFT



$$q_{\theta}(U) \approx \frac{e^{-S[U]}}{Z}$$

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ML black(-box) magic:

- Train generative models
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Output:

- Normalized density $q_{\theta}(U)$
- Approximation of target $p(U)$
- Embarrassingly parallel sampling



Not possible with standard HMC

Why Normalizing Flows for LFT?

- Lattice configurations are sampled i.i.d., thus reducing autocorrelation.
- Sampling is embarrassingly parallel, e.g., faster and more efficient.
- Direct estimation of thermodynamic observables (partition function, free energy, etc.).
- Inductive biases, e.g., symmetries, are easy to incorporate.
- The trained models can be used for interpolation (extrapolation) in parameter space.
- Transfer weights of flows trained on smaller systems to train on larger ones.
- ...




Plenary talk by Gurtej Kanwar (LATTICE 23)

What is NeuLat?

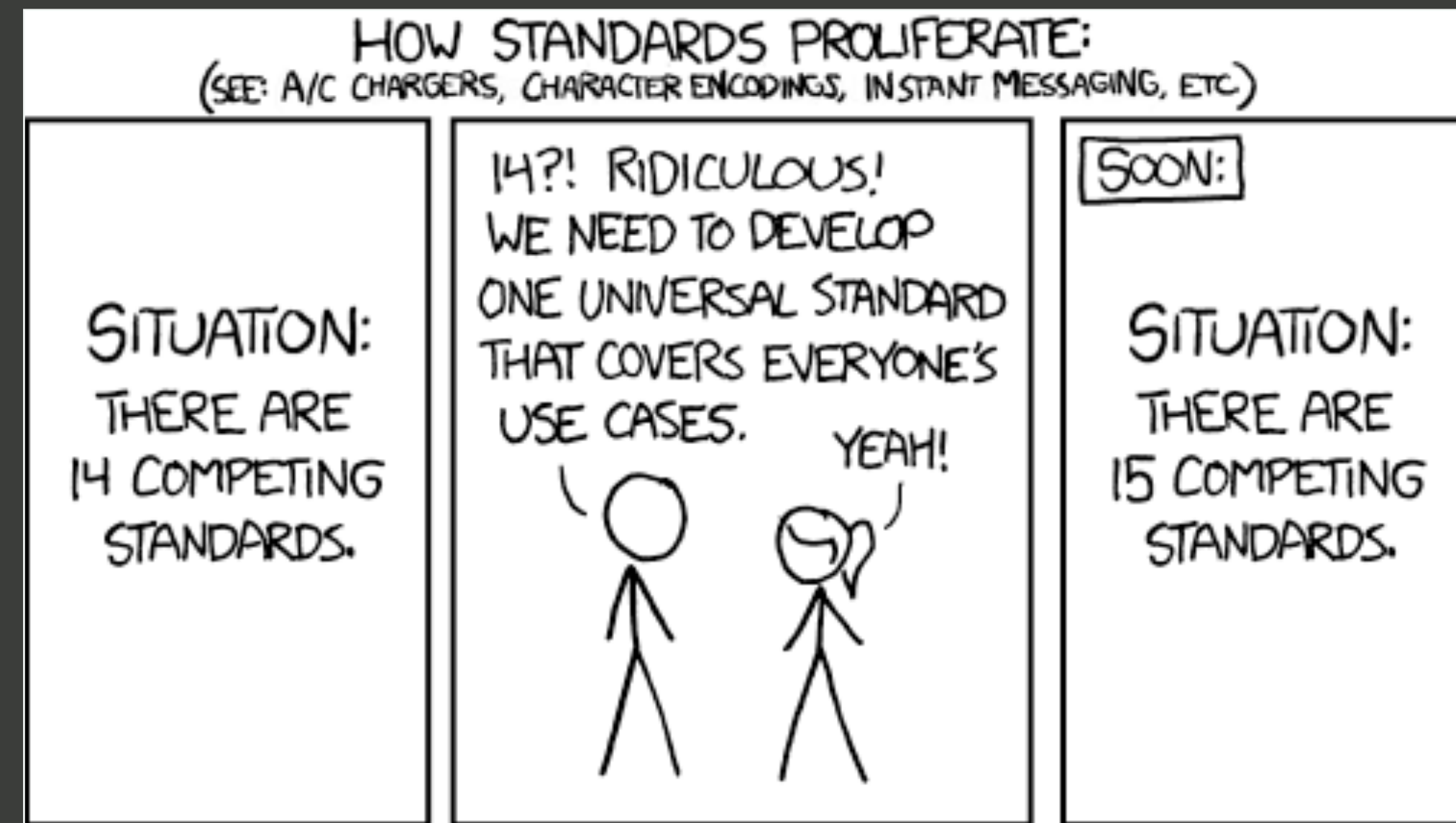
- NeuLat is an ML-based **software package** for benchmarking and test models for LFT e.g.,
 - 1+1D ϕ^4 -theory
 - 1+1D $U(1)$ gauge theory
- No such effort was made **yet** to combine existing tools into one software.
- NeuLat is meant to be a **community-wide** effort.
- The **core team** of NeuLat:
 - Expertise in ML **software development**.
 - Expertise in **LFT**.
 - **Various contributions to the field:** asymptotically unbiased estimators ([Nicoli K.A. et al.](#)), thermodynamic observables ([Nicoli K.A. et al.](#)), mode-dropping estimators ([Nicoli K.A. et al.](#)), path gradients ([Vaitl L. et al. \(2022\)](#)), and trivializing maps with flows ([Bacchio S. et al. \(2023\)](#)).

What are the benefits?

- Faster development of **new ideas**.
- Easier to **reproduce** newly published results (in the flow-based sampling community).
- Easier for people to **enter the community** and experiment with state-of-the-art techniques.
- Save the effort of **re-implementing** standard methods (e.g., architecture, estimators, etc.).
- Allow for immediate **extension to other fields** in physics (e.g., condensed matter physics).
- Similar **examples for ML frameworks** in other scientific communities:
 - SchNetPack - Deep Neural Networks for Atomistic Systems → 
 - BGFlow - Boltzmann Generators (BG) and other sampling methods

Why NeuLat?

- Many tools have been **independently** proposed.
- No **reference implementation** exists.
 - Often needs to reimplement existing code.
 - Different ML libraries.
 - Different code styles and structures.



Credits: xkcd.com/927

- Big (unnecessary) **overhead** (often seen also in the ML community).
- Excellent repositories are already available (though limited in scope).

- [fthmc: Field Transformation HMC](#)

- [l2hmc-qcd](#)  [l2hmc-qcd](#)

- [nflows](#)

- [GomalizingFlow](#)



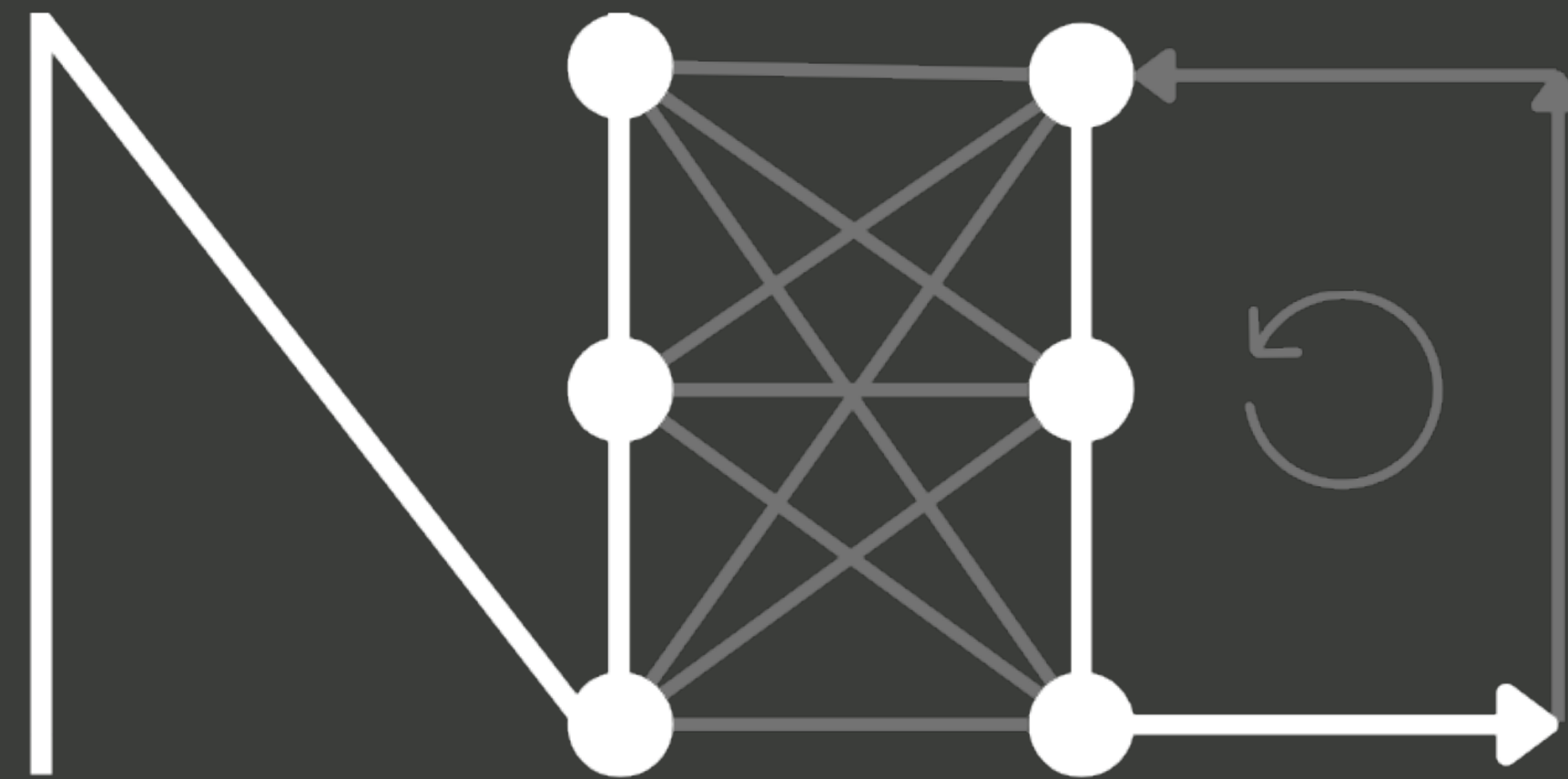
Julia package from A. Tomiya and collaborators!



Shout-out to Sam Foreman et al., for the great work!

NeuLat

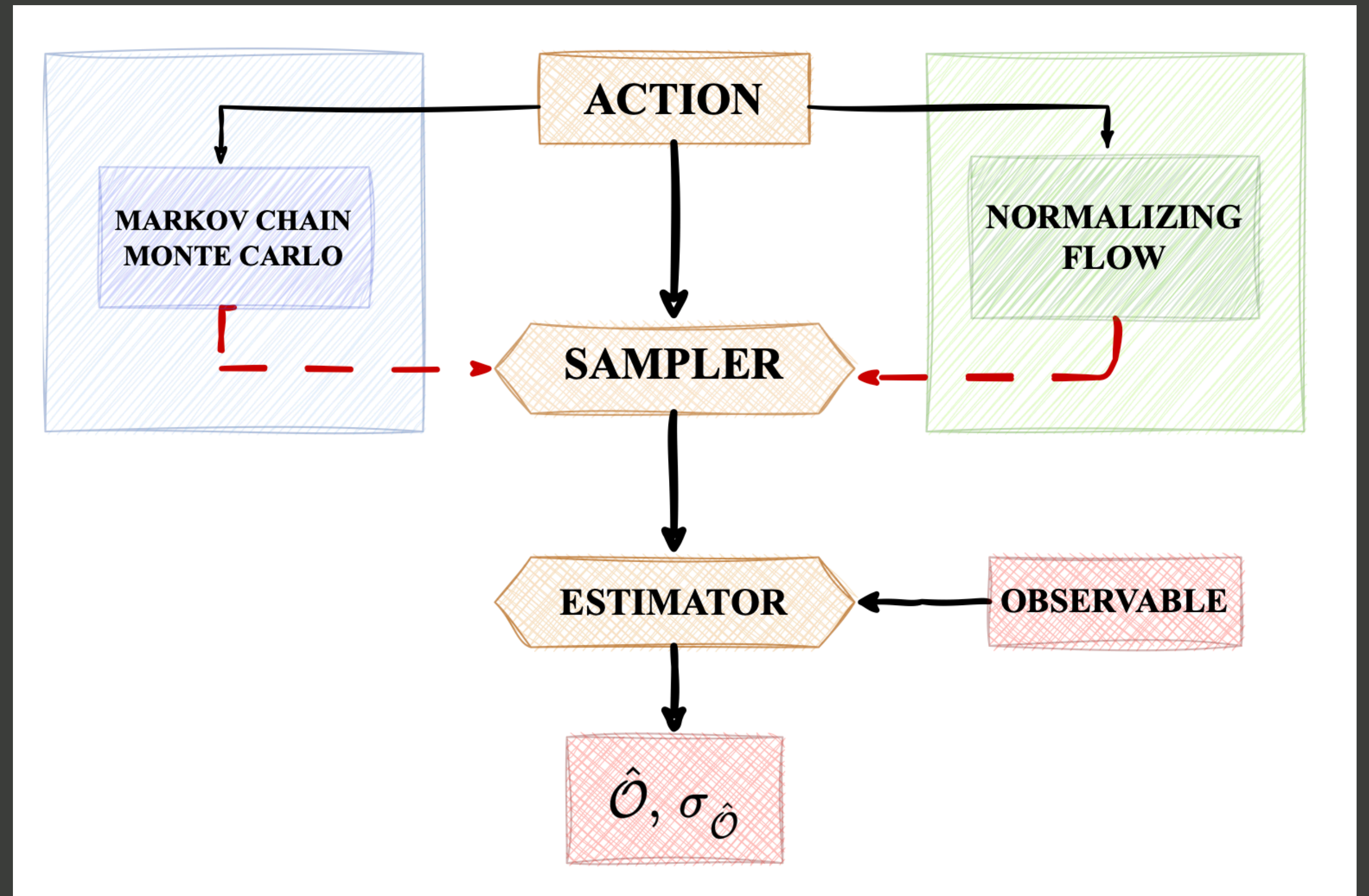
Goal: incorporate as many contributions from 5 years of research progress into a single software framework.



NEULAT

Software Overview

- PyTorch backend
- MCMC-based sampling
- Flow-based sampling (e.g., [nflows](#))
- Observable estimation (e.g., [py-uwerr](#))



Basic Workflow

Step 0: Define the action of the physical system to simulate.

Step 1: Build a Markov chain and a custom normalizing flow model.

Step 2: Specify loss and optimizer and train the flow model.

Step 3: Estimate observables using samples from HMC and trained flow.

```
1 n_samples, train_steps, batch = 1000, 1000, 500
2 action = Phi4Action(kappa=0.3, lamb=0.022)
3
4 hmc_chain = HMCMarkovChain(action, lat_shape=[16, 16], burn_in=100)
5 model = Flow(
6     lat_shape=[16, 16],
7     base_dist=NormalDistribution(),
8     coupling=NiceCoupling(),
9     n_couplings=6
10 )
11
12 optim = torch.optim.Adam(model.parameters(), lr=learning_rate)
13 loss_fn = ReverseKLLoss()
14 for _ in range(train_steps):
15     configs, log_probs = model.sample_and_log_prob(batch)
16     loss = loss_fn(action(configs), log_probs)
17     optim.zero_grad(); loss.backward(); optim.step()
18
19 obs = (Magnetization(), AbsMagnetization(), action)
20
21 flow_obs = IidEst(obs).evaluate(model.sample(n_samples))
22 hmc_obs = CorrelatedEst(obs).evaluate(hmc_chain.sample(n_samples))
```

Key Features

- **Density Estimation**: Learn approximations of targeted Boltzmann distributions $q_\theta \approx p$.
- **Sampling**:
 - MCMC implementations (HMC, Cluster algorithms, etc.).
 - Neural Importance Sampling (see [Albergo et al. \(2019\)](#), [Kanwar et al. \(2020\)](#), [Nicoli et al. \(2021\)](#)+ refs. therein).
 - Neural HMC (see same papers referenced above).
- **Estimation**:
 - Asymptotically unbiased estimators for physical observables (see [Nicoli et al. \(2020\)](#)).
 - Direct estimation of thermodynamic observables with flows and HMC (see [Nicoli et al. \(2021\)](#)).
 - Sampling in the presence of mode-collapse (see [Nicoli et al. \(2023\)](#)).
- **Customizable**: Easy to incorporate a new action/theory or customize new, equivariant flow-layers.

... and more!

Conclusion

- We presented **NeuLat**, a software for flow-based simulation of LFT.
- The software is meant to be accessible, **modular**, and easy to **extend** and **maintain**.
- This eliminates the **overhead** of re-implementing existing code between different formats.
- The first **release** of the software is planned for the **upcoming months**.
- NeuLat is aimed to be a **community-wide effort**. Get in touch if you would like to contribute.